Lecture 13: Chain Matrix Multiplication

CLRS Section 15.2

Revised April 17, 2003

Outline of this Lecture

- Recalling matrix multiplication.
- The chain matrix multiplication problem.
- A dynamic programming algorithm for chain matrix multiplication.

Recalling Matrix Multiplication

Matrix: An $n \times m$ matrix $A = [a[i,j]]$ is a two-dimensional array

$$A = \begin{bmatrix} a[1,1] & a[1,2] & \cdots & a[1,m-1] & a[1,m] \\ a[2,1] & a[2,2] & \cdots & a[2,m-1] & a[2,m] \\ \vdots & \vdots & & \vdots & \vdots \\ a[n,1] & a[n,2] & \cdots & a[n,m-1] & a[n,m] \end{bmatrix},$$

which has n rows and m columns.

Example: The following is a 4×5 matrix:

$$\begin{bmatrix} 12 & 8 & 9 & 7 & 6 \\ 7 & 6 & 89 & 56 & 2 \\ 5 & 5 & 6 & 9 & 10 \\ 8 & 6 & 0 & -8 & -1 \end{bmatrix}.$$

Recalling Matrix Multiplication

The product $C = AB$ of a $p \times q$ matrix A and a $q \times r$ matrix B is a $p \times r$ matrix given by

$$c[i,j] = \sum_{k=1}^{q} a[i,k]b[k,j]$$

for $1 \le i \le p$ and $1 \le j \le r$.

Example: If

$$A = \begin{bmatrix} 1 & 8 & 9 \\ 7 & 6 & -1 \\ 5 & 5 & 6 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 8 \\ 7 & 6 \\ 5 & 5 \end{bmatrix},$$

then

$$C = AB = \begin{bmatrix} 102 & 101 \\ 44 & 87 \\ 70 & 100 \end{bmatrix}.$$

Remarks on Matrix Multiplication

- If AB is defined, BA may not be defined.
- Quite possible that $AB \neq BA$.
- Multiplication is recursively defined by

$$A_1A_2A_3 \cdots A_{s-1}A_s = A_1(A_2(A_3 \cdots (A_{s-1}A_s))).$$

- Matrix multiplication is **associative** , e.g.,

$$A_1A_2A_3 = (A_1A_2)A_3 = A_1(A_2A_3),$$

so parenthenization does not change result.

Direct Matrix multiplication AB

Given a $p \times q$ matrix A and a $q \times r$ matrix B, the direct way of multiplying $C = AB$ is to compute each

$$c[i,j] = \sum_{k=1}^{q} a[i,k]b[k,j]$$

for $1 \leq i \leq p$ and $1 \leq j \leq r$.

Complexity of Direct Matrix multiplication:

Note that C has pr entries and each entry takes $\Theta(q)$ time to compute so the total procedure takes $\Theta(pqr)$ time.

Direct Matrix multiplication of ABC

Given a $p \times q$ matrix A, a $q \times r$ matrix B and a $r \times s$ matrix C, then ABC can be computed in two ways $(AB)C$ and $A(BC)$:

The number of multiplications needed are:

$$\begin{aligned} mult[(AB)C] &= pqr + prs, \\ mult[A(BC)] &= qrs + pqs. \end{aligned}$$

When $p = 5$, $q = 4$, $r = 6$ and $s = 2$, then

$$\begin{aligned} mult[(AB)C] &= 180, \\ mult[A(BC)] &= 88. \end{aligned}$$

A big difference!

Implication: The multiplication "sequence" (parenthesization) is important!!

The Chain Matrix Multiplication Problem

Given
dimensions $p_0, p_1, \ldots, p_n$
corresponding to matrix sequence A_1, A_2, …, A_n
where A_i has dimension $p_{i-1} \times p_i$,
determine the "multiplication sequence" that minimizes the number of scalar multiplications in computing $A_1 A_2 \cdots A_n$. That is, determine how to parenthisize the multiplications.

$$\begin{aligned} A_1A_2A_3A_4 &= (A_1A_2)(A_3A_4) \\ &= A_1(A_2(A_3A_4)) = A_1((A_2A_3)A_4) \\ &= ((A_1A_2)A_3)(A_4) = (A_1(A_2A_3))(A_4) \end{aligned}$$

Exhaustive search: $\Omega(4^n/n^{3/2})$.

Question: Any better approach? Yes – DP

Developing a Dynamic Programming Algorithm

Step 1: Determine the structure of an optimal solution (in this case, a parenthesization).

Decompose the problem into subproblems: For each pair $1 \leq i \leq j \leq n$, determine the multiplication sequence for $A_{i..j} = A_i A_{i+1} \cdots A_j$ that minimizes the number of multiplications.

Clearly, $A_{i..j}$ is a $p_{i-1} \times p_j$ matrix.

Original Problem: determine sequence of multiplication for $A_{1..n}$.

Developing a Dynamic Programming Algorithm

Step 1: Determine the structure of an optimal solution (in this case, a parenthesization).

High-Level Parenthesization for $A_{i..j}$
For any optimal multiplication sequence, at the last step you are multiplying two matrices $A_{i..k}$ and $A_{k+1..j}$ for some k. That is,

$$A_{i..j} = (A_i \cdots A_k)(A_{k+1} \cdots A_j) = A_{i..k}A_{k+1..j}.$$

Example

$$A_{3..6} = (A_3(A_4A_5))(A_6) = A_{3..5}A_{6..6}.$$

Here $k = 5$.

Developing a Dynamic Programming Algorithm

Step 1 – Continued: Thus the problem of determining the optimal sequence of multiplications is broken down into 2 questions:

- How do we decide where to split the chain (what is k)?

  (Search all possible values of k)

- How do we parenthesize the subchains $A_{i..k}$ and $A_{k+1..j}$?

  (Problem has optimal substructure property that $A_{i..k}$ and $A_{k+1..j}$ must be optimal so we can apply the same procedure recursively)

Developing a Dynamic Programming Algorithm

Step 1 – Continued:

Optimal Substructure Property: If final "optimal" solution of $A_{i..j}$ involves splitting into $A_{i..k}$ and $A_{k+1..j}$ at final step then parenthesization of $A_{i..k}$ and $A_{k+1..j}$ in final optimal solution must also be optimal for the subproblems "standing alone":

If parenthisization of $A_{i..k}$ was not optimal we could replace it by a better parenthesization and get a cheaper final solution, leading to a contradiction.

Similarly, if parenthisization of $A_{k+1..j}$ was not optimal we could replace it by a better parenthesization and get a cheaper final solution, also leading to a contradiction.

Developing a Dynamic Programming Algorithm

Step 2: Recursively define the value of an optimal solution.

As with the 0-1 knapsack problem, we will store the solutions to the subproblems in an array.

For $1 \leq i \leq j \leq n$, let $m[i, j]$ denote the minimum number of multiplications needed to compute $A_{i..j}$. The optimum cost can be described by the following recursive definition.

Developing a Dynamic Programming Algorithm

Step 2: Recursively define the value of an optimal solution.

$$m[i,j] = \begin{cases} 0 & i = j, \\ \min_{i \le k < j} (m[i,k] + m[k+1,j] + p_{i-1}p_k p_j) & i < j \end{cases}$$

Proof: Any optimal sequence of multiplication for $A_{i..j}$ is equivalent to some choice of splitting

$$A_{i..j} = A_{i..k}A_{k+1..j}$$

for some k, where the sequences of multiplications for $A_{i..k}$ and $A_{k+1..j}$ also are optimal. Hence

$$m[i,j] = m[i,k] + m[k+1,j] + p_{i-1}p_k p_j.$$

Developing a Dynamic Programming Algorithm

Step 2 – Continued: We know that, for some k

$$m[i,j] = m[i,k] + m[k+1,j] + p_{i-1}p_k p_j.$$

We don't know what k is, though
But, there are only $j - i$ possible values of k so we can check them all and find the one which returns a smallest cost.

Therefore

$$m[i,j] = \begin{cases} 0 & i = j, \\ \min_{i \le k < j} (m[i,k] + m[k+1,j] + p_{i-1}p_k p_j) & i < j \end{cases}$$

Developing a Dynamic Programming Algorithm

Step 3: Compute the value of an optimal solution in a bottom-up fashion.

Our Table: $m[1..n, 1..n]$.
$m[i,j]$ only defined for $i \le j$.

The important point is that when we use the equation

$$m[i,j] = \min_{i \le k < j} (m[i,k] + m[k+1,j] + p_{i-1}p_k p_j)$$

to calculate $m[i,j]$ we must have already evaluated $m[i,k]$ and $m[k+1,j]$.

Note that $k - i < j - i$ and $j - (k+1) < j - i$ so, to ensure that $m[i,j]$ is evaluated after $m[i,k]$ and $m[k+1,j]$ we simply let $\ell = 1, 2, \ldots, n-1$ and calculate all the terms of the form $m[i, i+\ell]$, $i = 1, \ldots n-\ell$ before we calculate the terms of the form $m[i, i+\ell+1]$, $i = 1, \ldots n-\ell-1$. That is, we calculate in the order

$m[1,2], m[2,3], m[3,4], \ldots, m[n-3,n-2], m[n-2,n-1], m[n-1,n]$
$m[1,3], m[2,4], m[3,5], \ldots, m[n-3,n-1], m[n-2,n]$
$m[1,4], m[2,5], m[3,6], \ldots, m[n-3,n]$
$\vdots$
$m[1,n-1], m[2,n]$
$m[1,n]$

Dynamic Programming Design Warning!!

When designing a dynamic programming algorithm there are two parts:

1. Finding an appropriate optimal substructure property and corresponding recurrence relation on table items. Example:

   $$m[i,j] = \min_{i \le k < j} \left(m[i,k] + m[k+1,j] + p_{i-1}p_k p_j\right)$$

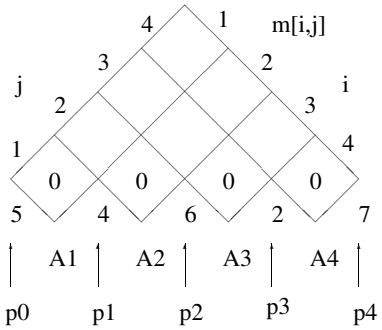
2. Filling in the table properly.
   This requires finding an ordering of the table elements so that when a table item is calculated using the recurrence relation, all the table values needed by the recurrence relation have already been calculated.

   In our example this means that by the time $m[i,j]$ is calculated all of the values $m[i,k]$ and $m[k+1,j]$ were already calculated.

Example for the Bottom-Up Computation

Example: Given a chain of four matrices A_1, A_2, A_3 and A_4, with $p_0 = 5$, $p_1 = 4$, $p_2 = 6$, $p_3 = 2$ and $p_4 = 7$. Find $m[1, 4]$.

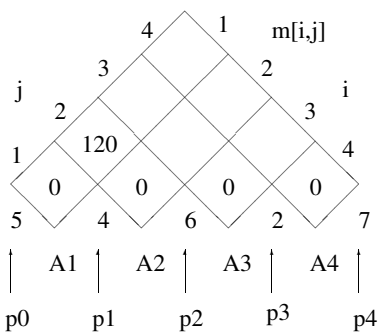
S0: Initialization



Example – Continued

Stp 1: Computing $m[1, 2]$ By definition

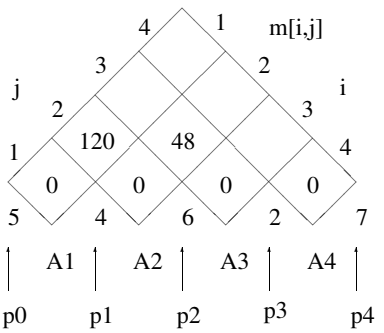
$$m[1,2] = \min_{1 \le k < 2} (m[1,k] + m[k+1,2] + p_0 p_k p_2)$$
$$= m[1,1] + m[2,2] + p_0 p_1 p_2 = 120.$$



Example – Continued

Stp 2: Computing $m[2, 3]$ By definition

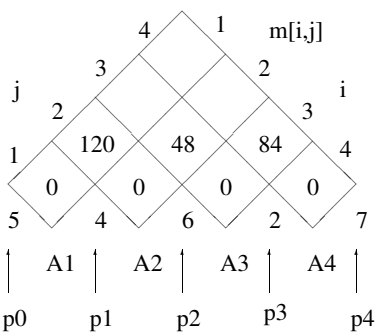
$$m[2,3] = \min_{2 \le k < 3} (m[2,k] + m[k+1,3] + p_1 p_k p_3)$$
$$= m[2,2] + m[3,3] + p_1 p_2 p_3 = 48.$$



Example – Continued

Stp3: Computing $m[3, 4]$ By definition

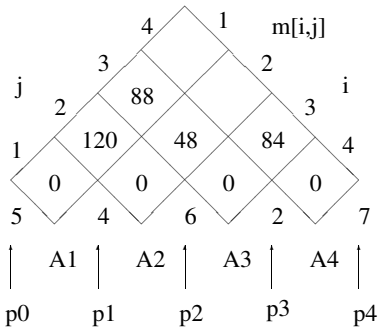
$$m[3,4] = \min_{3 \le k < 4} (m[3,k] + m[k+1,4] + p_2 p_k p_4)$$
$$= m[3,3] + m[4,4] + p_2 p_3 p_4 = 84.$$



Example – Continued

Stp4: Computing $m[1,3]$ By definition

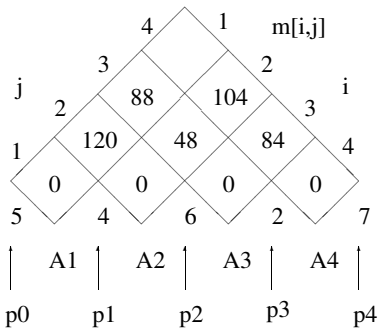
$$\begin{aligned} m[1,3] &= \min_{1\le k<3}(m[1,k]+m[k+1,3]+p_0p_kp_3) \\ &= \min\left\{\begin{array}{l} m[1,1]+m[2,3]+p_0p_1p_3 \\ m[1,2]+m[3,3]+p_0p_2p_3 \end{array}\right\} \\ &= 88. \end{aligned}$$



Example – Continued

Stp5: Computing $m[2,4]$ By definition

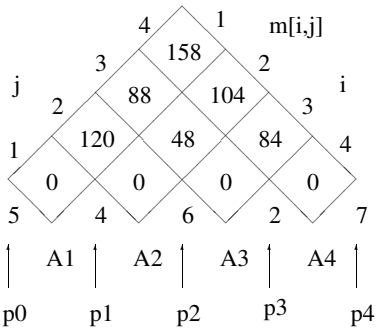
$$\begin{aligned} m[2,4] &= \min_{2\le k<4}(m[2,k]+m[k+1,4]+p_1p_kp_4) \\ &= \min\left\{\begin{array}{l} m[2,2]+m[3,4]+p_1p_2p_4 \\ m[2,3]+m[4,4]+p_1p_3p_4 \end{array}\right\} \\ &= 104. \end{aligned}$$



Example – Continued

St6: Computing $m[1,4]$ By definition

$$\begin{aligned} m[1,4] &= \min_{1\le k<4}(m[1,k]+m[k+1,4]+p_0p_kp_4) \\ &= \min\left\{\begin{array}{l} m[1,1]+m[2,4]+p_0p_1p_4 \\ m[1,2]+m[3,4]+p_0p_2p_4 \\ m[1,3]+m[4,4]+p_0p_3p_4 \end{array}\right\} \\ &= 158. \end{aligned}$$



We are done!

Developing a Dynamic Programming Algorithm

Step 4: Construct an optimal solution from computed information – extract the actual sequence.

Idea: Maintain an array $s[1..n, 1..n]$, where $s[i,j]$ denotes k for the optimal splitting in computing $A_{i..j} = A_{i..k}A_{k+1..j}$. The array $s[1..n, 1..n]$ can be used recursively to recover the multiplication sequence.

How to Recover the Multiplication Sequence?

$s[1,n]$	$(A_1 \cdots A_{s[1,n]})(A_{s[1,n]+1} \cdots A_n)$
$s[1,s[1,n]]$	$(A_1 \cdots A_{s[1,s[1,n]]})(A_{s[1,s[1,n]]+1} \cdots A_{s[1,n]})$
$s[s[1,n]+1,n]$	$(A_{s[1,n]+1} \cdots A_{s[s[1,n]+1,n]})\times$ $(A_{s[s[1,n]+1,n]+1} \cdots A_n)$
$\vdots$	$\vdots$

Do this recursively until the multiplication sequence is determined.

Developing a Dynamic Programming Algorithm

Step 4: Construct an optimal solution from computed information – extract the actual sequence.

Example of Finding the Multiplication Sequence:
Consider $n = 6$. Assume that the array $s[1..6, 1..6]$ has been computed. The multiplication sequence is recovered as follows.

$s[1, 6] = 3 \quad (A_1A_2A_3)(A_4A_5A_6)$
$s[1, 3] = 1 \quad (A_1(A_2A_3))$
$s[4, 6] = 5 \quad ((A_4A_5)A_6)$

Hence the final multiplication sequence is

$$(A_1(A_2A_3))((A_4A_5)A_6).$$

The Dynamic Programming Algorithm

```
Matrix-Chain(p, n)
{  for (i = 1 to n) m[i, i] = 0;
   for (l = 2 to n)
   {
      for (i = 1 to n − l + 1)
      {
         j = i + l − 1;
         m[i, j] = ∞;
         for (k = i to j − 1)
         {
            q = m[i, k] + m[k + 1, j] + p[i − 1] ∗ p[k] ∗ p[j];
            if (q < m[i, j])
            {
               m[i, j] = q;
               s[i, j] = k;
            }
         }
      }
   }
   return m and s; (Optimum in m[1, n])
}
```

Complexity: The loops are nested three deep.

Each loop index takes on $\leq n$ values.

Hence the time complexity is $O(n^3)$. Space complexity $\Theta(n^2)$.

Constructing an Optimal Solution: Compute $A_{1..n}$

The actual multiplication code uses the $s[i, j]$ value to determine how to split the current sequence. Assume that the matrices are stored in an array of matrices $A[1..n]$, and that $s[i, j]$ is global to this recursive procedure. The procedure returns a matrix.

```
Mult(A, s, i, j)
{
   if (i < j)
   {
      X = Mult(A, s, i, s[i, j]);
            X is now A_i ··· A_k, where k is s[i, j]
      Y = Mult(A, s, s[i, j] + 1, j);
            Y is now A_{k+1} ··· A_j
      return X ∗ Y;   multiply matrices X and Y
   }
   else return A[i];
}
```

To compute $A_1A_2 \cdots A_n$, call Mult$(A, s, 1, n)$.

Constructing an Optimal Solution: Compute $A_{1..n}$

Example of Constructing an Optimal Solution:
Compute $A_{1..6}$.

Consider the example earlier, where $n = 6$. Assume that the array $s[1..6, 1..6]$ has been computed. The multiplication sequence is recovered as follows.

Mult$(A, s, 1, 6)$, $s[1, 6] = 3$, $(A_1A_2A_3)(A_4A_5A_6)$
Mult$(A, s, 1, 3)$, $s[1, 3] = 1$, $((A_1)(A_2A_3))(A_4A_5A_6)$
Mult$(A, s, 4, 6)$, $s[4, 6] = 5$, $((A_1)(A_2A_3))((A_4A_5)(A_6))$
Mult$(A, s, 2, 3)$, $s[2, 3] = 2$, $((A_1)((A_2)(A_3)))((A_4A_5)(A_6))$
Mult$(A, s, 4, 5)$, $s[4, 5] = 4$, $((A_1)((A_2)(A_3)))(((A_4)(A_5))(A_6))$

Hence the product is computed as follows

$$(A_1(A_2A_3))((A_4A_5)A_6).$$