## 6.1-3

Let $i$ denote the index of the element at the root of a subtree of a heap. Then its left child is $\mathrm{A}[2 i]$ and its right child is $\mathrm{A}[2 i+1]$, if available. Recall that the definition of the max-heap property is: For every node $i$ other than root, $\mathrm{A}[\operatorname{Parent}(i)] \geq \mathrm{A}[i]$ where $\operatorname{Parent}(i)=\lfloor i / 2\rfloor$. Therefore,

For the left child $2 i, \mathrm{~A}[\operatorname{Parent}(2 i)]=\mathrm{A}[\lfloor 2 i / 2\rfloor]=\mathrm{A}[i] \geq \mathrm{A}[2 i]$
For the right child $2 i+1, \mathrm{~A}[\operatorname{Parent}(2 i+1)]=\mathrm{A}[(2 i+1) / 2\rfloor]=\mathrm{A}[L i+1 / 2\rfloor]=\mathrm{A}[i] \geq \mathrm{A}[2 i+1]$
Since $i$ is arbitrary, the largest element in a subtree of a heap is at the root of the subtree.

## 6.2-1

The array index begins at 1 :

| 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 27 | 17 | 3 | 16 | 13 | 10 | 1 | 5 | 7 | 12 | 4 | 8 | 9 | 0 |

1) 


2)

3)

4)


## 6.3-2

Notice that the conversion of an array into a heap is in a bottom-up manner. When processing node $i$, we want the subtrees of node $i$ already be heaps. In the other words, we want the node processing order to guarantee that the subtrees rooted at children of a node $i$ are heaps before HEAPIFY is executed at that node. Because the elements at the bottom have larger index number than their parents', we want the loop index $i$ in line 2 of BUILD-MAX_HEAP to decrease to 1 .
[We may not obtain a heap if the process starts from the root to the bottom. Try apply the algorithm on $<4,1,3,8,6>]$.

## 7.1-1

[This solution is done using the algorithm from the lecture, which also appears in the first edition of the textbook. It now appears as Q7-1 on page 159.]

```
pivot = A[1]=13
```

1) 

$i \quad x$

| 13 | 19 | 9 | 5 | 12 | 8 | 7 | 4 | 11 | 2 | 6 | 21 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

2) 

$x, i$

| 13 | 19 | 9 | 5 | 12 | 8 | 7 | 4 | 11 | 2 | 6 | 21 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

3) 

$i$

| 6 | $x, j$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

4) 


5)

| $i$ | $i$ |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 6 | 2 | 9 | 5 | 12 | 8 | 7 | 4 | 11 | 19 | 13 | 21 |

6) 

| 6 | 2 | 9 | 5 | 12 | 8 | 7 | 4 | 11 | 19 | 13 | 21 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |

Return 9 (index begins at 1)

## 7.2-4

The performance of quicksort is at best $\Theta(n \lg n)$. However, the performance of insertion-sort is at best $\Theta(n)$. Now consider the algorithm of insertion-sort on page 24 of the textbook. For an almost-sorted input, the whileloop will be executed a few times more than in the best case. Since the extra steps are still constant, the performance of insertion-sort is still $\Theta(n)$. Indeed, using the analysis similar to the one on page $24, \mathrm{~T}(n)=\mathrm{c} 1 * \mathrm{n}$ $+\mathrm{c} 2 *(\mathrm{n}-1)+\mathrm{c} 4 *(\mathrm{n}-1)+\mathrm{c} 5 *(\mathrm{n}-1+\mathrm{k} 1)+\mathrm{c} 6 * \mathrm{k} 2+\mathrm{c} 7 * \mathrm{k} 2+\mathrm{c} 8 *(\mathrm{n}-1)=\Theta(\mathrm{n})$, where $\mathrm{k} 1, \mathrm{k} 2$ are some extra steps.

On the other hand, no matter if the input is already sorted or not, the best-case of quicksort is $\Theta(n \lg n)$. Thus, when the input is almost-sorted, insertion-sort beats quicksort.

## 8.3-3

Base case:
Let $\mathrm{d}=1$. We only sort on the least significant digit. Obviously, the radix sort works on the least sig. digit.
Hypothesis:
Radix sort works on numbers with arbitrary digits, using an intermediate stable-sort.
We need to assume that radix sort uses a stable sort to sort array A on digit i so the intermediate sort is stable. Assume also that, for $\mathrm{d}=\mathrm{k}$, the least k -th sig. digits of the numbers are sorted properly.

Inductive case:
For $\mathrm{d}=\mathrm{k}+1$, use a stable sort to sort array A on digit $\mathrm{k}+1$. Since the least k -th digits are sorted properly by a stable sort (by assumption), after a stable sort is used on digit $\mathrm{k}+1$, the order of the least k -th digits is preserved. Thus, the least $k+1$ th digits of $n$ numbers are in order.
[Not all numbers in array need to have the same number $d$. The empty digit can be filled with ' 0 ']
By induction, radix sort works.

## 8.6

c)

Suppose there are $2 n$ elements: $a_{1}, a_{2}, a_{3}, \ldots, a_{2 n}$ such that $a_{1} \leq a_{2} \leq \ldots \leq a_{2 n}$. Moreover, we have two sorted arrays A1 and A2, where $a_{i}$ in A1 and $a_{i+1}$ in A2. Assume that $a_{i}$ will not be compared with $a_{i+1}$. Then,

Case 1: $a_{i}$ is compared with an element $a \neq a_{i+1}$ in A2. However, $a$ must be less than $a_{i+1}$ because $a_{i}$ and $a_{i+1}$ are consecutive. Thus, all such elements in A2 will be merged, and $a_{i}$ will finally be compared with $a_{i+1}$.

Case 2: $a_{i+l}$ is compared with an element $b \neq a_{i}$ in A1. However, $b$ must be less than $a_{i}$ because $a_{i}$ and $a_{i+l}$ are consecutive. Thus, all such elements in A1 will be merged, and $a_{i+l}$ will finally be compared with $a_{i}$.

By contradiction, if two elements are consecutive in the sorted order and from opposite lists, then they must be compared.
d)

Suppose there are $2 n$ elements: $a_{1}, a_{2}, a_{3}, \ldots, a_{2 n}$ such that $a_{1} \leq a_{2} \leq a_{3} \leq \ldots \leq a_{2 n}$. The first sorted list A1 $=<a_{1}$, $a_{3}, \ldots, a_{2 n-1}>$ and the second A2=<a2, $a_{4}, \ldots, a_{2 n}>$. By part c, we must have $a_{1} \leq ? a_{2} \leq ? a_{3} \leq$ ? ... $\leq$ ? $a_{2 n}$ where $\leq$ ? denotes comparison. Therefore, there are $2 \mathrm{n}-1$ comparisons for n elements in each list.

